

# GAP: DIFFERENTIALLY PRIVATE GRAPH NEURAL NETWORKS WITH AGGREGATION PERTURBATION

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Joint work with Ali Shahin Shamsabadi, Aurélien Bellet, and Daniel Gatica-Perez

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- Graph Neural Networks (GNNs) are state-of-the-art algorithms for learning on graphs
  - Tasks: node classification, link prediction, ...
  - Applications: recommendation systems, credit issuing, traffic forecasting, drug discovery, ...

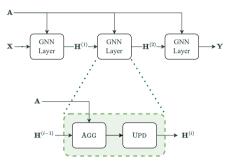
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  - Link stealing attack [He et al., 2021a, Wu et al., 2021]
  - Node membership inference attack [Olatunji et al., 2021, He et al., 2021b]

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Our Goal: Making GNNs privacy-preserving using **Differential Privacy** 

- A: Adjacency matrix
- X: Input node features
- Y: Predicted node labels
- H<sup>(i)</sup>: Hidden node representations of layer *i* **AGG**: Aggregation function
  - e.g., summation:  $AGG(H, A) = A^T \cdot H$
- **UPD**: Learnable update function
  - e.g., an MLP



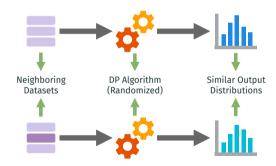
- ► An algorithm is executed on the private dataset and the output is publically released
- ► An adversary should not be able to learn about the private dataset by analyzing the output



#### Differential Privacy [Dwork et al., 2006]

**Randomized** algorithm A is  $(\epsilon, \delta)$ -differentially private if for all **neighboring** datasets  $D \simeq D'$  and all sets of outputs S:

 $\Pr[A(D) \in S] \le e^{\epsilon} \Pr[A(D') \in S] + \delta$ 



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- ► The probability bound captures how much protection we get
  - $\epsilon$  quantifies information leakage
    - Often called privacy budget
  - $\delta$  allows for a small probability of failure
    - Usually very small ( $\delta \ll$  inverse number of records)

#### Differential Privacy [Dwork et al., 2006]

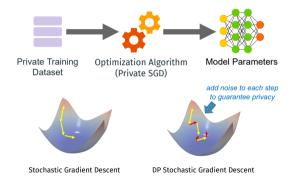
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- The neighboring relation captures what is protected
  - Standard DP: D and D' differ by at most one record
  - Edge-level DP: *D* and *D'* are graphs differing by at most one edge
  - Node-level DP: D and D' are graphs differing by at most one node (and all its adjacent edges)

# DIFFERENTIALLY PRIVATE ML

Differentially private learning is possible with noisy gradient descent



#### DP-SGD Algorithm [Abadi et al., 2016]

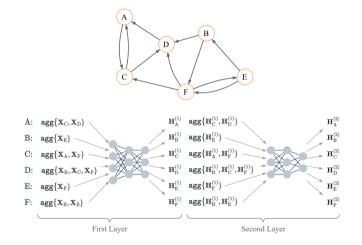
**input** : Data  $\{\vec{x}_1, \dots, \vec{x}_N\}$ , learning rate  $\eta$ , batch size *B*, epochs *T*, **clipping threshold** *C*, **noise variance**  $\sigma^2$ , 1 Initialize  $\vec{\theta}_0$  randomly

for  $t \in [T \cdot \frac{N}{B}]$  do

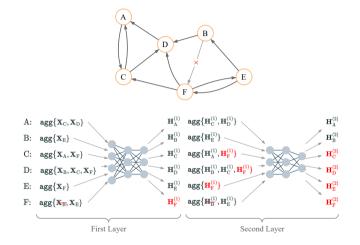
2 Sample a batch  $\vec{B}_t$  by selecting each  $\vec{x}_i$  independently with probability  $\frac{B}{N}$ 

3For each 
$$\vec{x}_i \in \vec{B}_t$$
:  $\vec{g}_t(\vec{x}_i) \leftarrow \nabla_{\vec{\theta}_t} L(\vec{\theta}_t, \vec{x}_i)$ // compute per-sample gradients4 $\vec{g}_t(\vec{x}_i) \leftarrow \text{clip}(\vec{g}_t(\vec{x}_i), C)$ // clip gradients to max norm C5 $\vec{g}_t \leftarrow \frac{1}{B} \left( \sum_{\vec{x}_i \in \vec{B}_t} \vec{g}_t(\vec{x}_i) + \mathcal{N}(0, \sigma^2 \vec{l}) \right)$ // add Gaussian noise with variance  $\sigma^2$ 6 $\vec{\theta}_{t+1} \leftarrow \vec{\theta}_t - \eta \vec{g}_t$ // SGD stependoutput:  $\vec{\theta}_{\underline{IN}}$ 

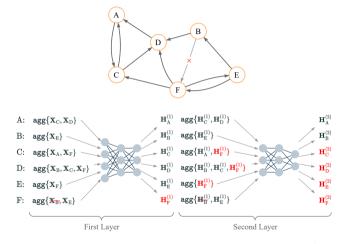
# DP GNN CHALLENGES: EXPLODING SENSITIVITY



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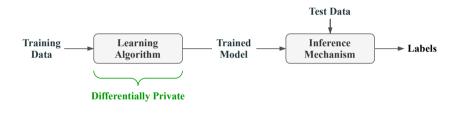


# DP GNN CHALLENGES: EXPLODING SENSITIVITY



The number of affected outputs =  $O(\max \text{ degree}^{\text{num layers}})$ 

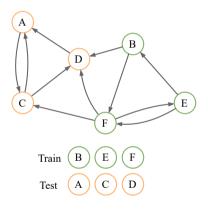
#### Private Learning: Standard Neural Nets



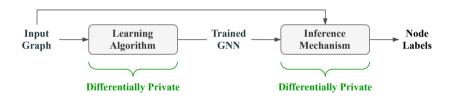
Inference is independent of the training data

# DIFFERENTIALLY PRIVATE GNN CHALLENGES: INFERENCE PRIVACY

- ► GNN re-uses graph data for inference
- Private information leaks at inference, even with a private model



#### Private Learning: Graph Neural Nets



Both training and inference should be private

# OUR APPROACH: AGGREGATION PERTURBATION

- The sensitivity of a single aggregation step is easily computed
  - Only one node is affected for edge-level DP
  - Maximum D nodes are affected for node-level DP (D is maximum degree)
- Aggregation Perturbation: adding noise to output of the aggregation step
  - Prevents the exploding sensitivity problem by composing differentially private aggregation steps
  - Ensures inference privacy
- Applying aggregation perturbation to the conventional GNNs is **costly** 
  - Every forward pass of the model consumes privacy budget
  - The excessive noise results in poor performance

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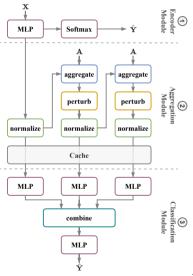
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#### Need to tailor the GNN architecture to the private learning setting!

# GNN with Aggregation Perturbation (GAP)

#### 1. Encoder Module

- Learns to encode node features into lower-dimensional representations
- Does not use graph adjacency information



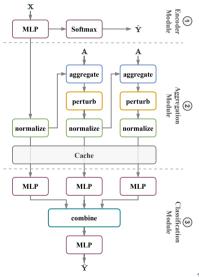
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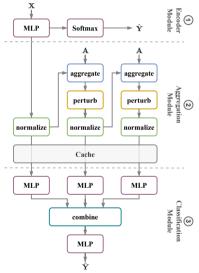
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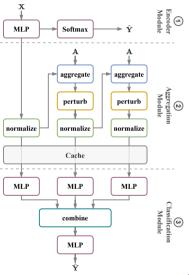
#### 3. Classification Module

- Learns to perform node-wise classification based on aggregated node representations
- Does not re-use graph adjacency information



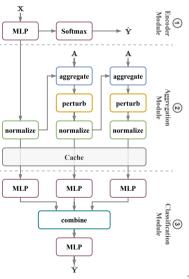
# Advantages of GAP Architecture

✓ Edge-level DP



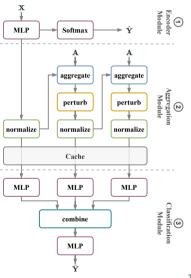
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- $\checkmark~$  Node-level DP through combination with DP-SGD
  - For bounded-degree graphs



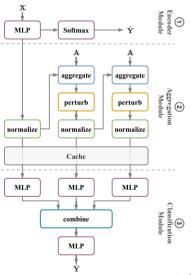
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# ADVANTAGES OF GAP ARCHITECTURE

- ✓ Edge-level DP
- $\checkmark$  Node-level DP through combination with DP-SGD
  - For bounded-degree graphs
- ✓ Multi-hop aggregations
- $\checkmark~$  Zero-cost inference privacy



# For any $\delta \in (0, 1)$ , number of hops $K \ge 0$ , and noise standard deviation $\sigma > 0$ , GAP's training algorithm satisfies edge-level $(\epsilon, \delta)$ -DP with:

$$\epsilon = \frac{K}{2\sigma^2} + \sqrt{\frac{2K\log\left(1/\delta\right)}{\sigma}}$$

For any  $\delta \in (0, 1)$ , number of nodes N, batch-size 0 < B < N, number of epochs T, gradient clipping threshold C > 0, number of hops  $K \ge 0$ , maximum cut-off degree  $D \ge 1$ , and noise standard deviation  $\sigma > 0$ , GAP's training algorithm satisfies node-level  $(\epsilon, \delta)$ -DP with:

$$\epsilon \leq \min_{\alpha} 2T \frac{N}{B} \frac{1}{\alpha - 1} \log \left\{ \left(1 - \frac{B}{N}\right)^{\alpha - 1} \left(\alpha \frac{B}{N} - \frac{B}{N} + 1\right) + {\alpha \choose 2} \left(\frac{B}{N}\right)^2 \left(1 - \frac{B}{N}\right)^{\alpha - 2} e^{\frac{c^2}{\sigma^2}} + \sum_{l=3}^{\alpha} {\alpha \choose l} \left(1 - \frac{B}{N}\right)^{\alpha - l} \left(\frac{B}{N}\right)^l e^{(l-1)(\frac{c^2l}{2\sigma^2})} \right\} + \frac{DK\alpha}{2\sigma^2} + \frac{\log(1/\delta)}{\alpha - 1}$$

s.t.  $\alpha > 1$ .

#### ► Task: Node Classification

DATASET	CLASSES	Nodes	Edges	Features	Avg. Degree
Facebook	6 Year	26,406 User	2,117,924 Friendship	501	62
Reddit	8 Community	116,713 Розт	46,233,380 Mutual User	602	209
Amazon	10 Category	1,790,731 Ргодист	80,966,832 Mutual Purchase	100	22

# **EXPERIMENT SETTINGS: COMPETING METHODS**

#### Edge-Level Private Methods

- GAP-EDP: Our edge-level private method
- SAGE-EDP: Graph-SAGE with adjacency matrix perturbation [Wu et al., 2021]
- MLP: Simple MLP model that does not use the graph edges
- Node-Level Private Methods
  - GAP-NDP: Our node-level private method
  - SAGE-NDP: 1-layer Graph-SAGE with gradient perturbation [Daigavane et al., 2021]
  - MLP-DP: Simple MLP model trained with DP-SGD

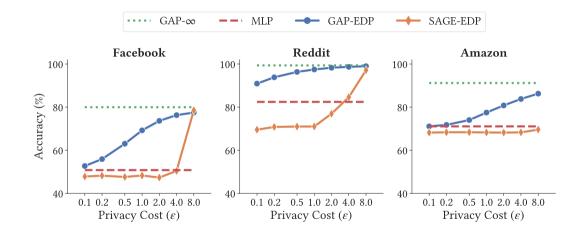
#### ► None-Private Methods

- GAP-∞: GAP without noise
- SAGE-∞: Standard Graph-SAGE [Hamilton et al., 2017]

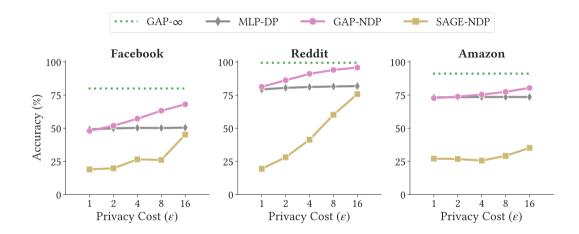
## Accuracy of Non-Private Methods

Method	Facebook	Reddit	Amazon
GAP- $\infty$	$80.0 \pm 0.48$	<b>99.4 ± 0.02</b>	91.2 ± 0.07
SAGE- $\infty$	$83.2 \pm 0.68$	99.1 ± 0.01	<b>92.7</b> ± <b>0.09</b>

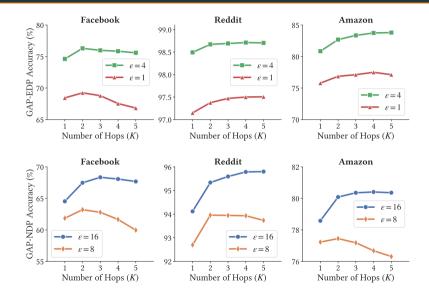
# EDGE-LEVEL DP ACCURACY-PRIVACY TRADE-OFF



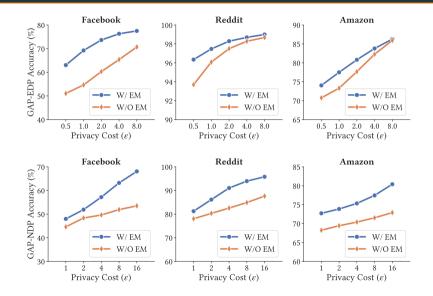
# NODE-LEVEL DP ACCURACY-PRIVACY TRADE-OFF



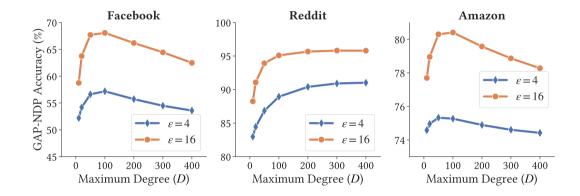
# **EFFECT OF THE NUMBER OF HOPS**



# **EFFECT OF THE ENCODER MODULE**



# **EFFECT OF THE MAXIMUM DEGREE**



- ► Implementing DP in GNNs is challenging
  - Exploding sensitivity
  - Inference privacy
- ► Our contribution: GAP
  - Ensures both edge-level and node-level DP
  - Supports multi-hop aggregations
  - Provides inference privacy

# THANK YOU!

Questions?

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